



Different types of Operating Systems

- There are several architectures which all require a different OS:
 - Desktop PCs
 - Parallel Systems
 - Distributed Systems
 - Clustered Systems
 - Real-time Systems
 - Embedded Systems



Desktop Systems

- **Personal Computers** – computer system dedicated to a single user.
- I/O devices – keyboards, mice, display screens, small printers.
- User convenience and responsiveness.
- Can adopt technology developed for larger operating system
- Often individuals have sole use of computer and do not need advanced CPU utilization or protection features.
- May run several different types of operating systems (Windows, MacOS, UNIX, Linux)



Parallel Systems

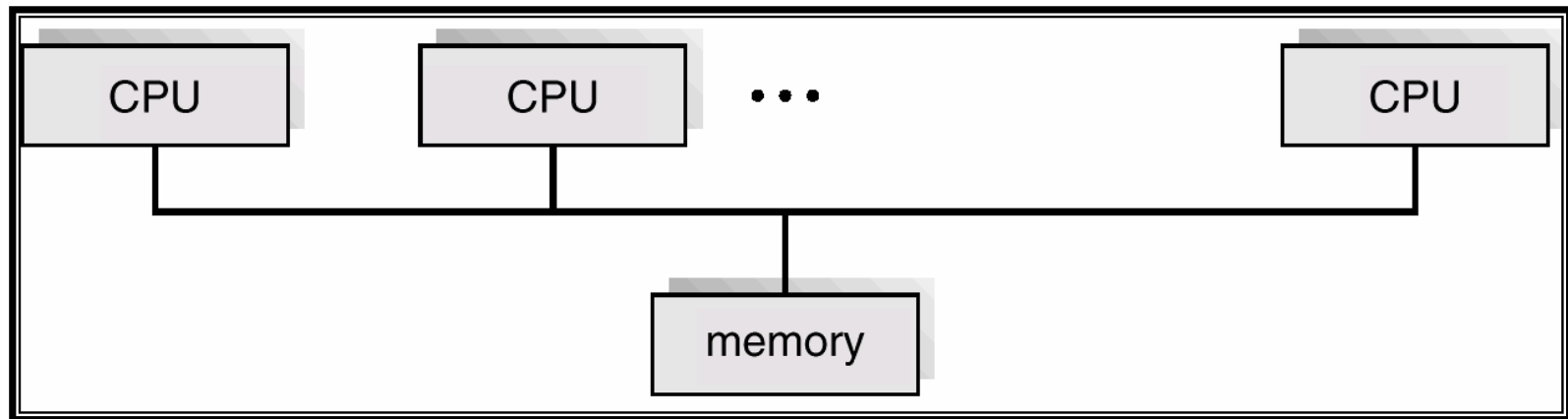
- Multiprocessor systems with more than one CPU in close communication.
- *Tightly coupled system* – processors share memory and the internal clock; communication usually takes place through the shared memory.
- Advantages of parallel system:
 - Increased *throughput*
 - Economical
 - Increased reliability
 - graceful degradation
 - fail-soft systems



Parallel Systems (Cont.)

- *Symmetric multiprocessing (SMP)*
 - Each processor runs an identical copy of the operating system.
 - The OS code is usually shared.
 - Many processes can run at once without performance deterioration.
 - Most modern operating systems have SMP support.
 - OS has to cater for protection of data.
- *Asymmetric multiprocessing*
 - Each processor is assigned a specific task; master processor schedules and farms work to slave processors.
 - More common in extremely large systems like mainframes with hundreds of processors.

Symmetric Multiprocessing Architecture

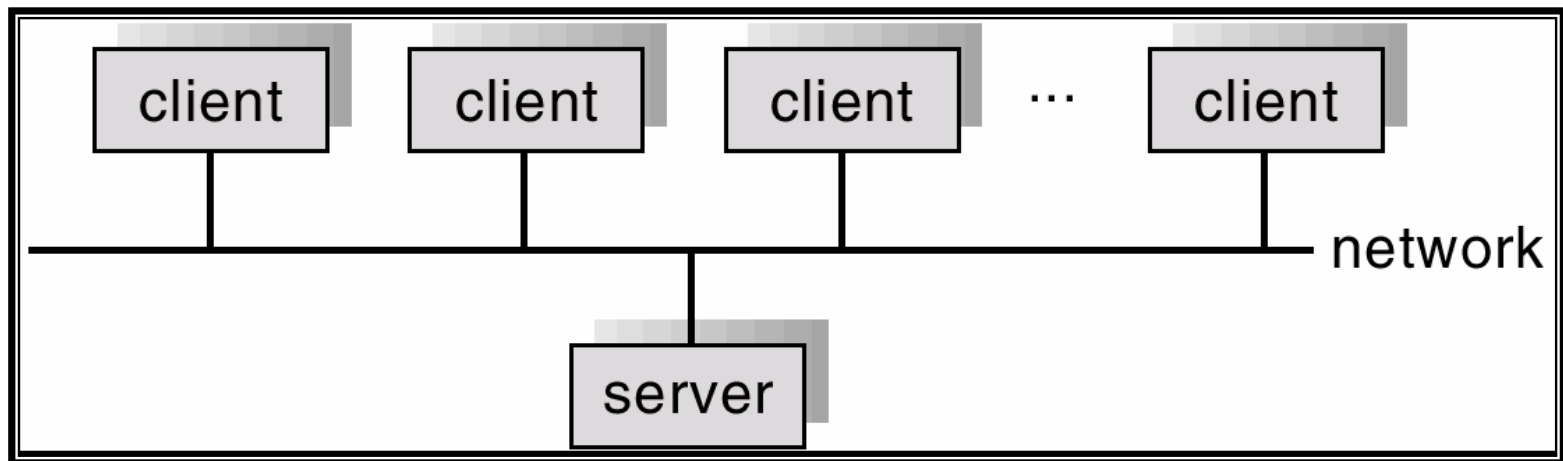




Distributed Systems

- Distribute the computation among several physical processors.
- *Loosely coupled system* – each processor has its own local memory; processors communicate with one another through various communications lines, such as high-speed buses or network communication.
- Advantages of distributed systems.
 - Resources Sharing
 - Computation speed up – load balancing
 - Scalability
 - Reliability
 - Fail-Safe
 - Communications
- May make use of commodity platforms.
- OS has to cater for resource sharing.
- May be either client-server or peer-to-peer systems.

General Structure of Distributed Client-Server





Clustered Systems

- Clustering allows two or more systems to share storage.
- Provides high reliability.
- *Asymmetric clustering*: one server runs the application while other servers standby.
- *Symmetric clustering*: all N hosts are running the application.
- Used mainly for database applications where a file server exists.



Real-Time Systems

- Often used as a control device in a dedicated application such as controlling scientific experiments, medical imaging systems, industrial control systems, and some display systems.
- Well-defined fixed-time constraints.
- Real-Time systems may have either *hard* or *soft* real-time.



Real-Time Systems (Cont.)

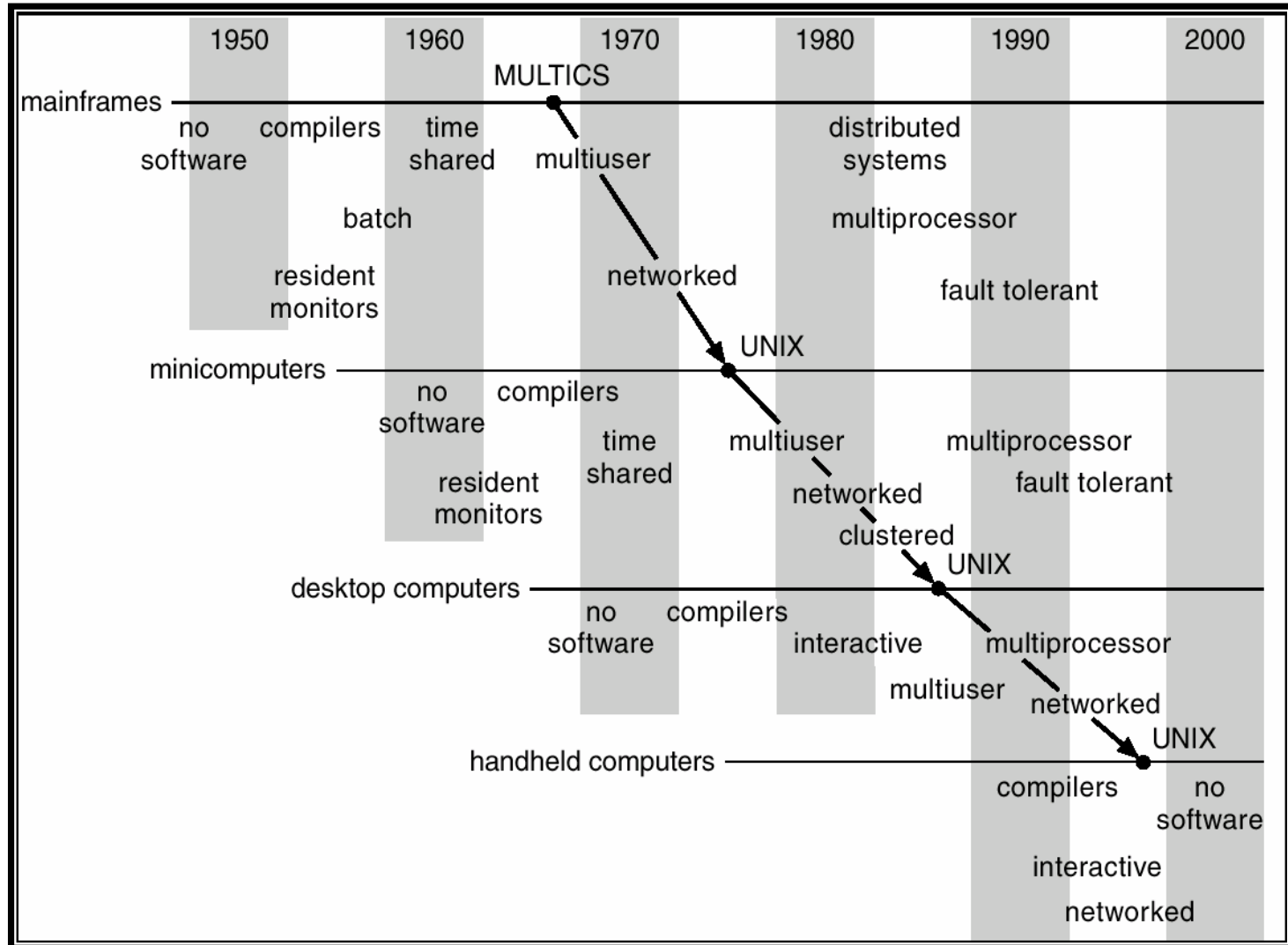
- **Hard real-time:**
 - Secondary storage limited or absent, data stored in short term memory, or read-only memory (ROM)
 - Conflicts with time-sharing systems, usually not supported by general-purpose operating systems.
- **Soft real-time**
 - Limited utility in industrial control of robotics
 - Quality of Service
 - Useful in applications (multimedia, virtual reality) requiring advanced operating-system features.



Embedded Systems

- Personal Digital Assistants (PDAs)
- Cellular telephones
- Issues:
 - Limited memory
 - Slow processors
 - Small display screens.
- Usually most features of typical OS's are not included at the expense of the developer.
- Emphasis is on I/O operations.
- Memory Management and Protection features are usually absent.

TimeLine





End of Section

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