

# *Conversion Masters in IT (MIT)*

## *AI as Representation and Search*

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(Machine Learning: EDSM + Version Search Space)

Lecture 006

# *State Merging Algorithms*

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- Starting from the APTA we merge states together in order to label the unlabeled states in the APTA
  - By merging we introduce cycles in the APTA.
  - With every merge the hypothesis becomes more general.
  - We keep on merging (compatible) states until there are no more compatible merges.
  - Finally we output the final hypothesis.
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# *Evidence Driven State Merging (EDSM)*

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- ❑ What heuristic do we apply to this search ?
  - ❑ Or rather we need to determine the order of the merges. The heuristic determines the order of how states are merged.
  - ❑ *NOTE:* Different orders give different hypothesis. Why ?
  - ❑ EDSM orders the merges by giving each possible merge a compatibility score.
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# Version Space Search

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- Version Space search (Mitchell 1978, 1982) illustrates the implementation of inductive learning as search through a concept space (the set of all concept descriptions consistent with training examples).
  
  - The representation of learned knowledge:
    - Eg the concept ball
    - General concept
      - Size (X, Y)  $\wedge$  color (X, Z)  $\wedge$  shape (X, round)
    - Less General concept
      - Size (X, small)  $\wedge$  color (X, Z)  $\wedge$  shape (X, round)
  
  - A set of operations. Given a set of training instances, the learner must construct a generalisation that satisfies its goals. Therefore we need operations to manipulate representations. *Eg Generalisation or specializing symbolic expressions.*
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# Generalisation Operators

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- Size (obj1, small)  $\wedge$  colour (obj1, red)  $\wedge$  shape (obj1, round)
    - Replacing a single constant with a variable produces the generalizations:
      - Size (obj1, X)  $\wedge$  colour (obj1, red)  $\wedge$  shape (obj1, round)
      - Size (obj1, small)  $\wedge$  colour (obj1, X)  $\wedge$  shape (obj1, round)
      - Size (obj1, small)  $\wedge$  colour (obj1, red)  $\wedge$  shape (obj1, X)
      - Size (X, small)  $\wedge$  colour (X, red)  $\wedge$  shape (X, round)
  - 1. Replacing constants with variables
  - 2. Dropping conditions from a conjunction expression
  - 3. Adding a disjunction to an expression
  - 4. Replacing a property with it's parent in a class hierarchy. Eg primary colour is a superclass of red.
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# *Concept Space and Heuristic search*

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- The concept space is the representation language, together with the operations described in previous slide, defines a space of potential concept definitions.
  - Heuristic Search. The learner must search this space to find the desired concept. Learning programs must commit to a direction or order of search (inductive bias).
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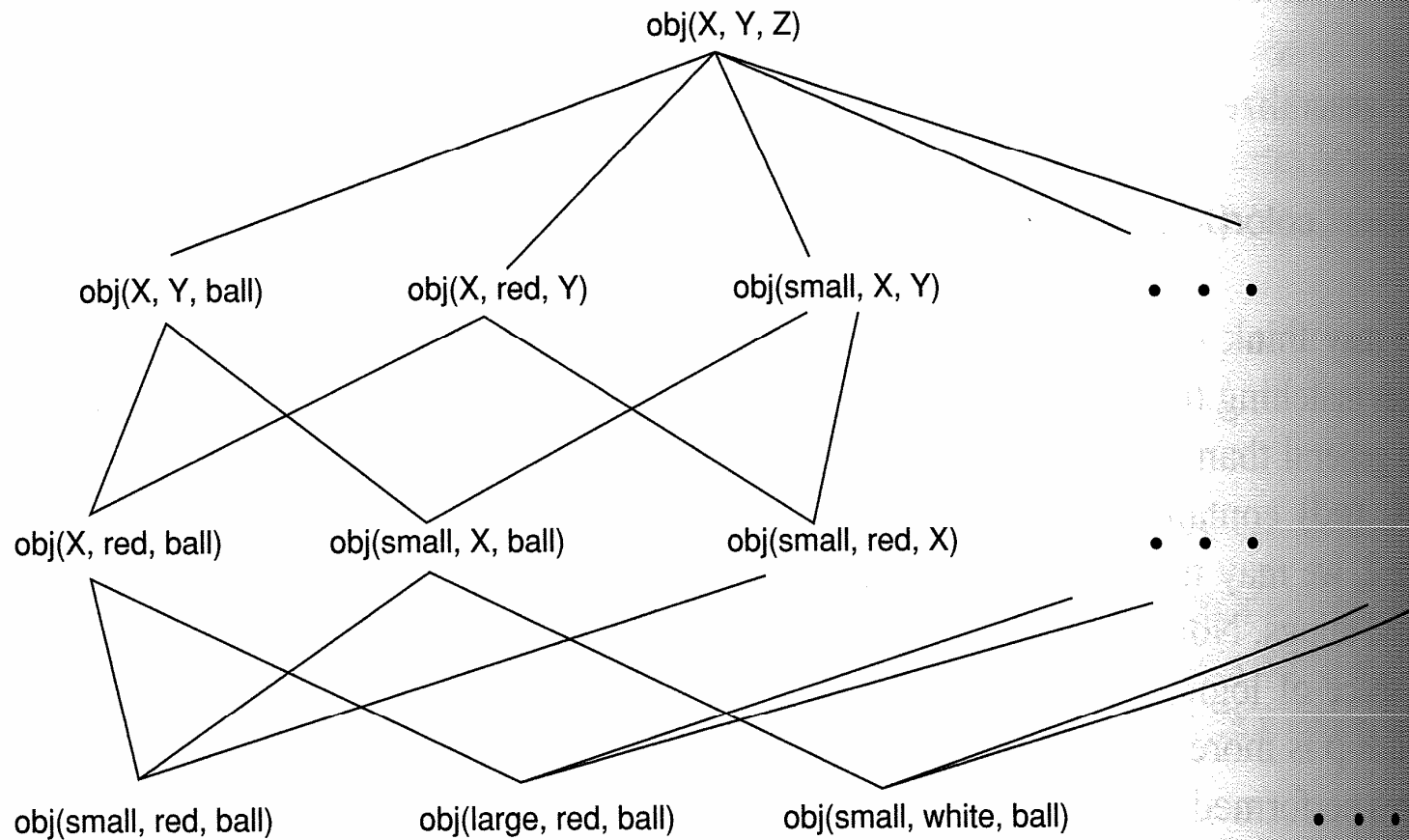
# *The Candidate Elimination Algorithm*

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- Algorithm works by reducing the size of the version space as more examples become available.
  
  - One can reduce the space in two ways:
    - In a specific to general direction; or
    - In a general to specific direction
  
  - The candidate elimination algorithm combines these two approaches (bi-directional search)
  
  - The algorithms are data driven; as in they generalize with respect to regularities found in the training data.
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# *Eg of a concept space $obj(X, Y, Z) \dots$*

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# *Specific to general search for hypothesis set S*

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- Initialize S to the first +ve training instance;
  - N is the set of all -ve instances seen so far;
  
  - For each +ve instance p
    - Begin
    - For every s in S, if s does not match p, replace s with its most specific generalization that matches p;
    - Delete from S all hypothesis more general than some other hypothesis in S
    - Delete from S all hypothesis that match a previously observed -ve instance in N;
    - End;
  - For each -ve instance n
    - Begin
      - Delete all members of S that match n;
      - Add n to N to check future hypothesis for overgeneralization;
    - End;
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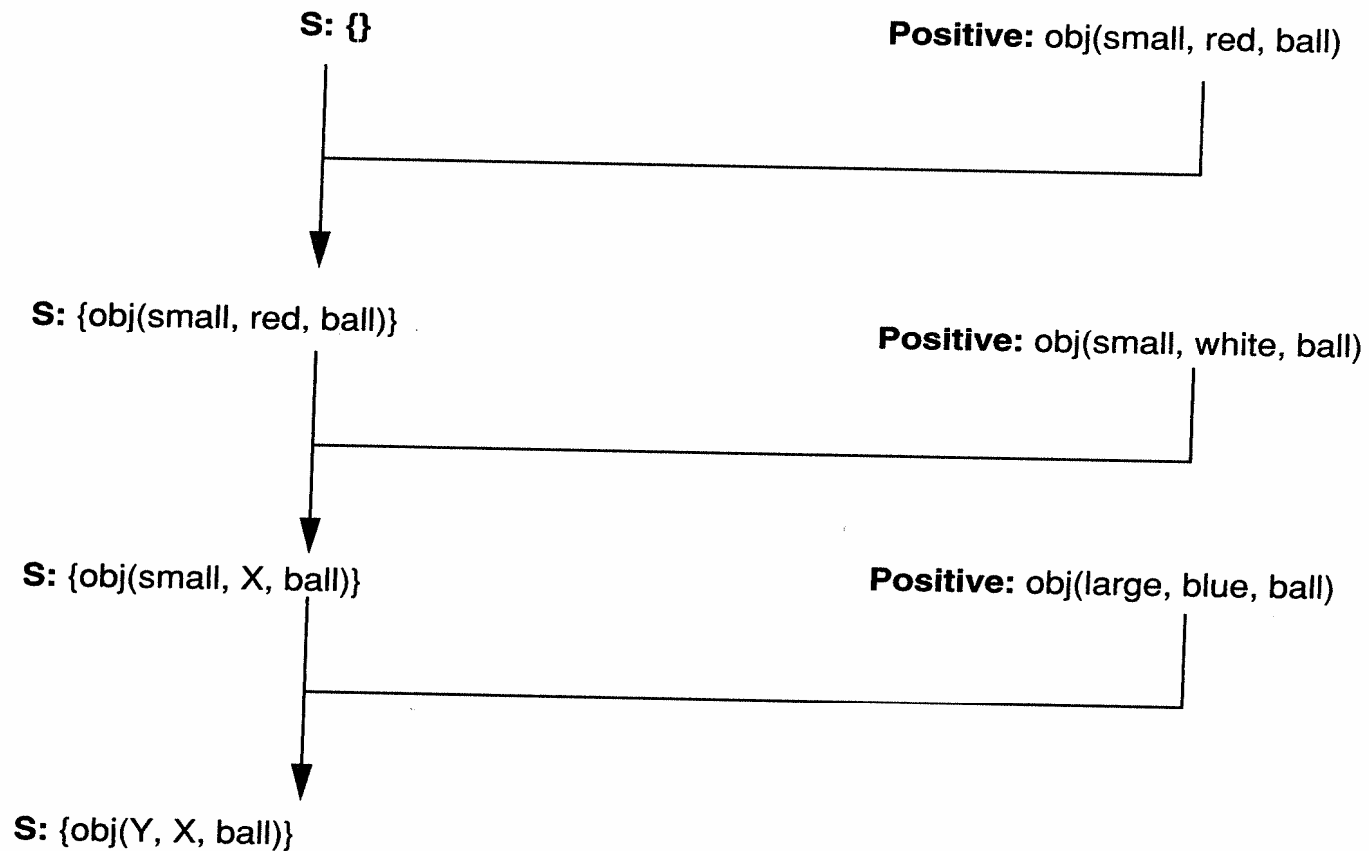
# *General to specific search for hypothesis set S*

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- Initialize G to contain the most general concept in the space;
  - P contains all +ve examples seen so far;
  
  - For each -ve instance n
    - Begin
    - For every g in G that matches n, replace g with its most general specialization that do not match n;
    - Delete from G all hypothesis more specific than some other hypothesis in G;
    - Delete from G all hypothesis that fail to match some +ve examples in P;
    - End;
  - For each +ve instance p
    - Begin
      - Delete from G all hypothesis that fail to match p;
      - Add p to P;
    - End;
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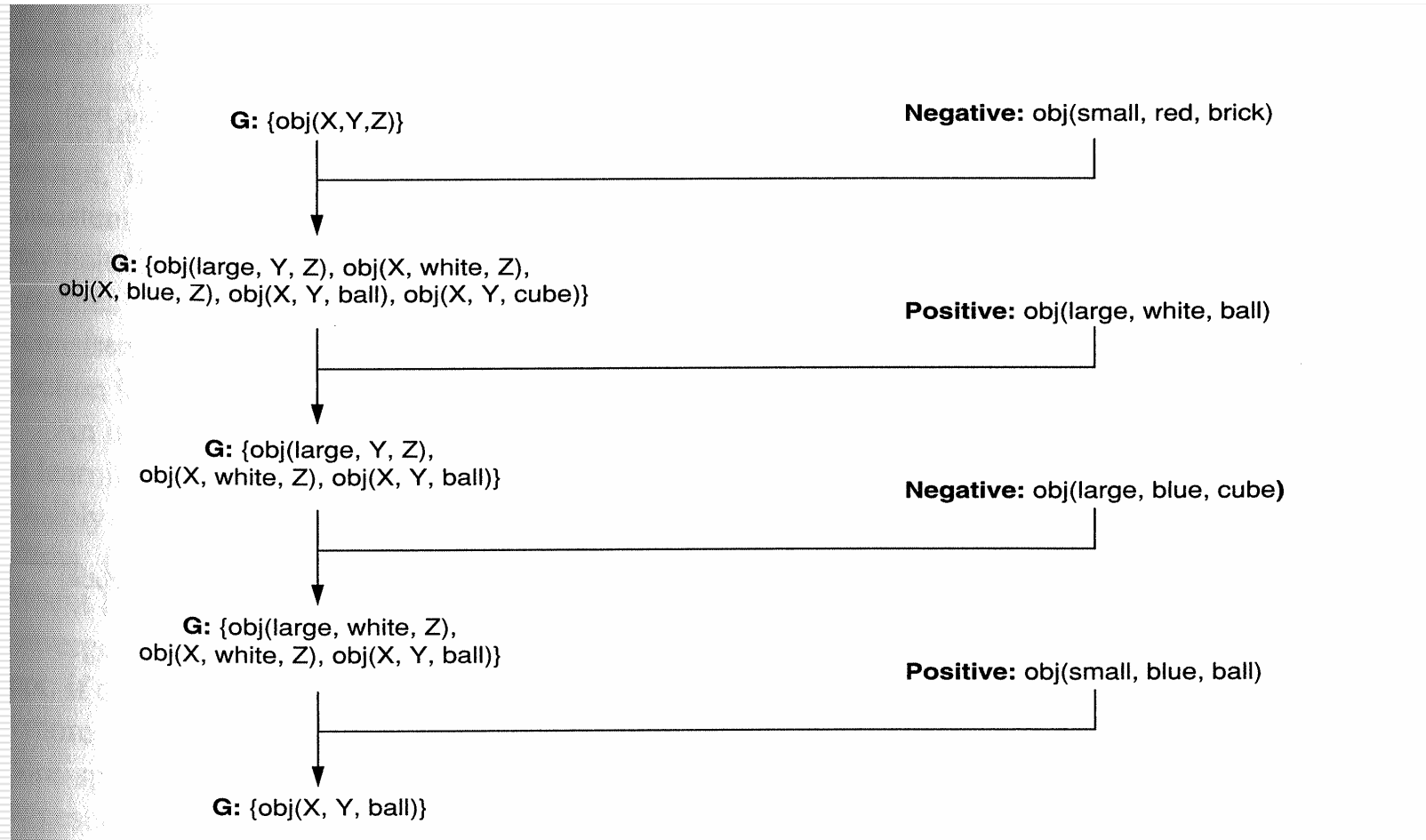
# *Eg of using the specific → generic algo*

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# Eg of using the generic $\rightarrow$ specific algo

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# *Combining the two together*

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- Keep both sets S and G.
  - S contains the most specific description;
  - G contains the most generic;
  - If  $G=S$  and both are singletons, then the algorithm has found a single concept that is consistent with all the data and the algorithm halts;
  - If G and S become empty, then there is no concept that covers all +ve instances and none of the -ve instances.
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# Eg Combining the two together

